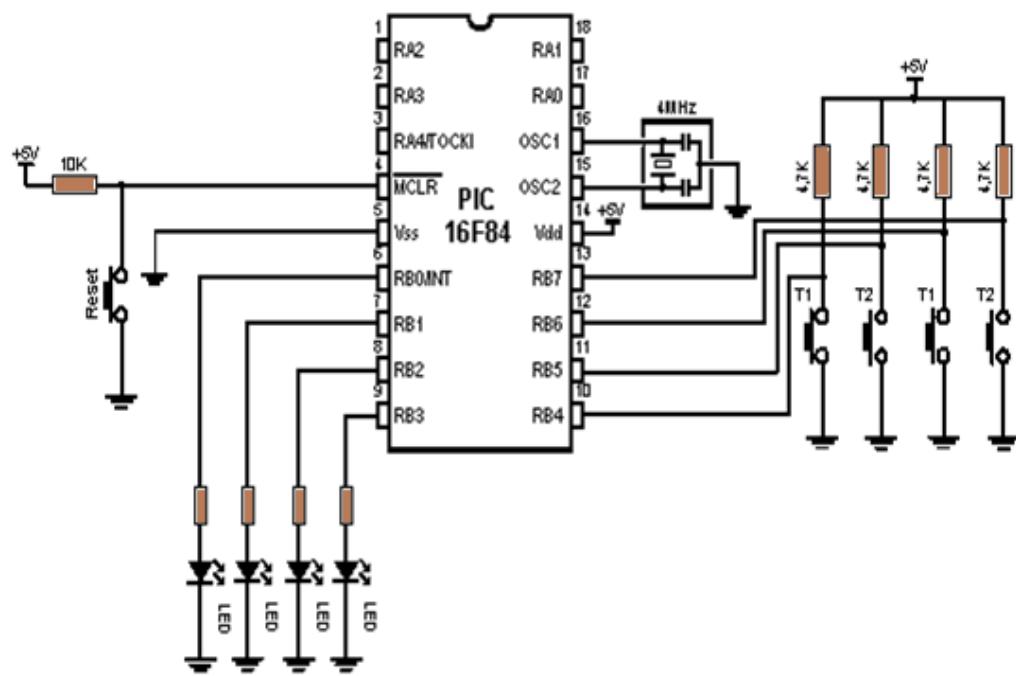


Interruption sur broches RB4-RB7



```

;***** Declaring and configuring a microcontroller *****
PROCESSOR 16f84
#include "p16f84.inc"
__CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Structure of program memory *****
org 0x00
goto Main
org 0x04
goto ISR

Main
[   bsf 3,5
    movlw 0xf0          ;Higher four LED diodes are on
    movwf TRISB
    bcf 3,5
    movlw 0xff
    movwf PORTB
    bsf INTCON,RBIE    ;interrupt upon pin change enabled
    bsf INTCON,GIE    ;all interrupts are enabled

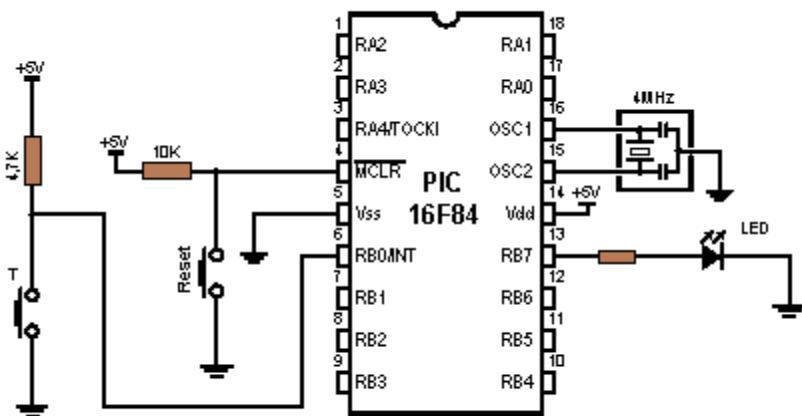
Loop
    goto Loop           ;Main loop

ISR
    bcf INTCON,RBIF    ;Clears the flag that indicates RB interrupt
    ;took place thus enabling detection of
    ;new interrupts in main program
    ;Determining which button caused the interrupt
    btfs PORTB,7
    goto Led0
    btfs PORTB,6
    goto Led1
    btfs PORTB,5
    goto Led2
    btfs PORTB,4
    goto Led3
    retfie

Led0
    bcf PORTB,0          ;Switch off diode LD0
    retfie
Led1
    bcf PORTB,1          ;Switch off diode LD1
    retfie
Led2
    bcf PORTB,2          ;Switch off diode LD2
    retfie
Led3
    bcf PORTB,3          ;Switch off diode LD3
    retfie

```

Interruption sur la broche RB0



```

;***** Declaring and configuring a microcontroller *****
PROCESSOR 16f84
#include "p16f84.inc"
_CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Structure of program memory *****
org 0x00
goto Main
org 0x04
goto ISR

Main
  bcf 3,5
  movlw b'00000001'           ;RB0 is input, the rest are output
  movwf TRISB
  bcf OPTION_REG, INTEDG      ;interrupt occurs at falling edge
  bcf OPTION_REG, NOT_RBPU    ;internal pull-up resistors are off
  bcf 3,5
  clrf PORTB
  bcf PORTB,7                 ;Only LED diode PORTB,7 is on
  bcf INTCON, INTE             ;interrupt RB0 enabled
  bcf INTCON, GIE              ;all interrupts enabled

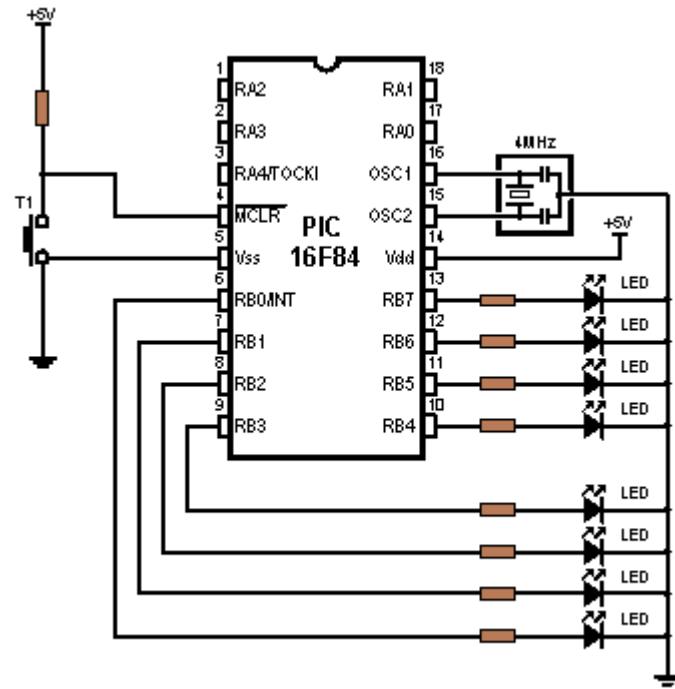
Loop
  goto Loop                   ;Main loop

ISR
  bcf INTCON, INTF            ;Clears the flag that indicates RB interrupt
                                ;took place thus enabling detection of
                                ;new interrupts in main program
  btfss PORTB,7               ;Is LED7 on?
  goto Lab1
  bcf PORTB,7                 ;If true switch off LED7
  retfie

Lab1
  bsf PORTB,7                 ;If false switch on LED7
  retfie
End

```

Interruption sur débordement du Timer TMRO



```

;***** Declaring and configuring a microcontroller *****
PROCESSOR 16f84
#include "p16f84.inc"

_CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Declaring variables *****
cnt      equ 0x0c

;***** Structure of program memory *****
ORG      0x00      ;Reset vector
goto    Main

ORG      0x04      ;Interrupt vector
goto    ISR

Main
  bsf 3,5
  clrf  TRISB      ;Port B is output
  movlw .255
  movwf TRISA      ;Port A is input
  movlw  B'10000100' ;Set prescaler to TMRO

  movwf  OPTION_REG ;ps = 32=> TMRO is incremented every 32us
  bcf 3,5
  clrf  PORTB      ;All the diodes are off by default
  bsf   INTCON,TOIE ;Enable TMRO interrupt
  movlw  .96         ;Initialize TMRO
  ;Overflow occurs every (255-96)*32us=5.088ms

  movwf  TMRO      ;Start the counter
  bsf   INTCON,GIE  ;Interrupts are globally enabled
  clrf  cnt

loop
  goto  loop      ;Remain at this line

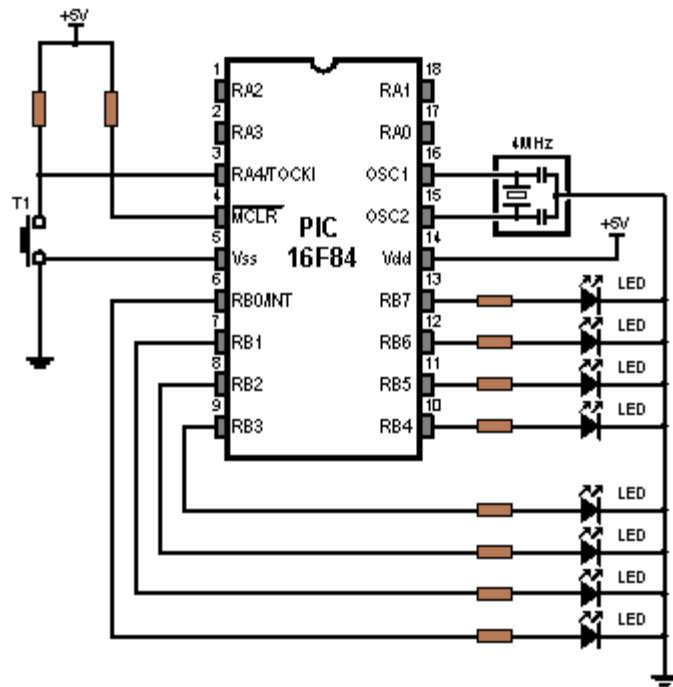
ISR
  movlw  .96         ;Initialize TMRO to ensure next interrupt
  ;in 5ms
  movwf  TMRO
  bcf   INTCON,TOIF ;clear int. flag

  incf  cnt,F
  movlw .196        ;Has one second elapsed?(ls~196*5.088 ms)
  subwf  cnt,W
  btfss STATUS,Z
  retfie
  comf  PORTB,f    ;If true, complement the values of port B
  clrf  cnt          ;and set the initial value of variable cnt
  retfie            ;If false, exit the interrupt routine

End      ;End of program

```

Interruption sur débordement du TMRO connecté à une entrée externe (TOCKI)



```

;***** Declaring and configuring a microcontroller *****

PROCESSOR 16f84
#include "p16f84.inc"

__CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Declaring constants *****

num_rev equ .156;

;***** Structure of program memory *****

ORG 0x00 ; Reset vector
goto Main

ORG 0x04 ; Interrupt vector
goto ISR

Main
[ bsf 3,5
  clrf TRISB ; Port B is input
  movlw B'11111'
  movwf TRISA ; Port A is output
  movlw B'10100001' ; External impulses on TOCKI increment TMRO
  movwf OPTION_REG ; ps = 4 TMRO increments every 4 impulses
  bcf 3,5 ; i.e. 1 revolution = 4 impulses
  clrf PORTB ; All diodes are off by default
  bsf INTCON,TOIE ; Enable TMRO interrupt
  movlw .256 ; Initialize TMRO so that overflow
  sublw num_rev ; occurs every 100 revolutions,
  ; i.e. TMRO is set to 256-156=100

  movwf TMRO ; Start the counter
  bsf INTCON,GIE ; Interrupts are globally enabled

```

```
loop          ; Display number of remaining revolutions
             ; on port B
movf TMRO,W
sublw .256      ; number of remaining revolutions=256-TMRO
movwf PORTB
goto loop       ; Remain at this line

ISR
movlw .256      ; Initialize TMRO so it can count next
                   ; 100 revolutions
sublw broj_obrtaja
movwf TMRO

bcf INTCON,TOIF ; clear int. flag
retfie           ; return to main program

End           ; End of program
```