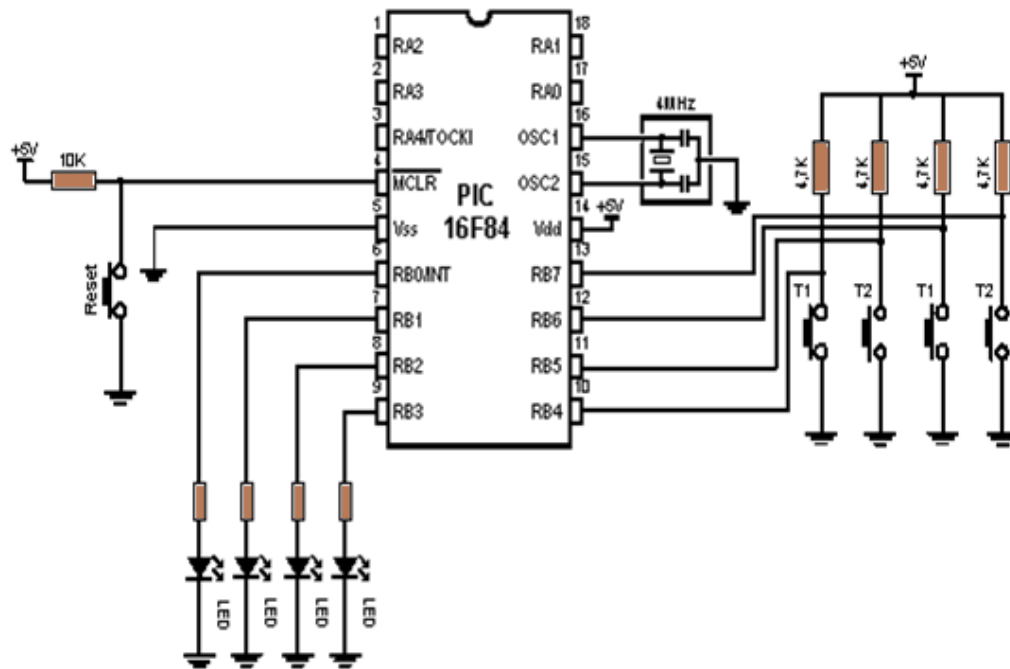


Interruption sur broches RB4-RB7



```

;***** Declaring and configuring a microcontroller *****
PROCESSOR 16f84
#include "p16f84.inc"
__CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Structure of program memory *****

org 0x00
goto Main
org 0x04
goto ISR

Main
[ bsf 3,5
  movlw 0xf0          ;Higher four LED diodes are on
  movwf TRISB
  bcf 3,5
  movlw 0xff
  movwf PORTB
  bsf INTCON,RBIE     ;interrupt upon pin change enabled
  bsf INTCON,GIE      ;all interrupts are enabled

Loop
  goto Loop           ;Main loop

ISR
  bcf INTCON,RBIF     ;Clears the flag that indicates RB interrupt
                      ;took place thus enabling detection of
                      ;new interrupts in main program
  btfss PORTB,7       ;Determining which button caused the interrupt
  goto Led0
  btfss PORTB,6
  goto Led1
  btfss PORTB,5
  goto Led2
  btfss PORTB,4
  goto Led3
  retfie

Led0
  bcf PORTB,0         ;Switch off diode LD0
  retfie

Led1
  bcf PORTB,1         ;Switch off diode LD1
  retfie

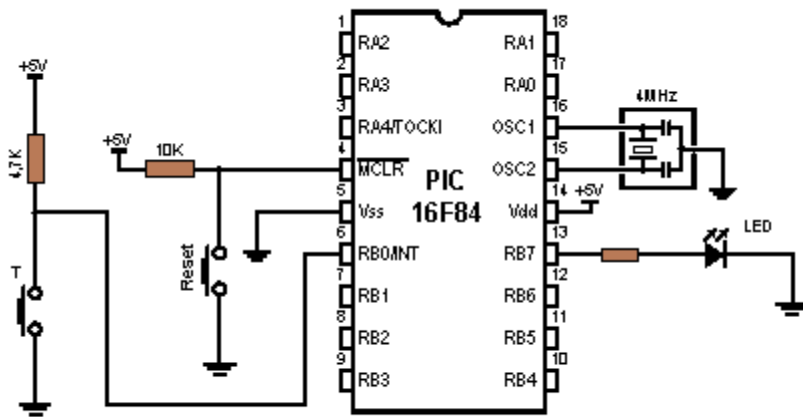
Led2
  bcf PORTB,2         ;Switch off diode LD2
  retfie

Led3
  bcf PORTB,3         ;Switch off diode LD3
  retfie

End

```

Interruption sur la broche RB0



```

;***** Declaring and configuring a microcontroller *****
PROCESSOR 16f84
#include "p16f84.inc"
_CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Structure of program memory *****
org 0x00
goto Main
org 0x04
goto ISR

Main
    bsf 3,5
    movlw b'00000001'      ;RB0 is input, the rest are output
    movwf TRISB
    bcf OPTION_REG,INTEDG   ;interrupt occurs at falling edge
    bsf OPTION_REG,NOT_RBPU ;internal pull-up resistors are off
    bcf 3,5
    clrf PORTB
    bsf PORTB,7             ;Only LED diode PORTB,7 is on
    bsf INTCON,INTE         ;interrupt RB0 enabled
    bsf INTCON,GIE          ;all interrupts enabled

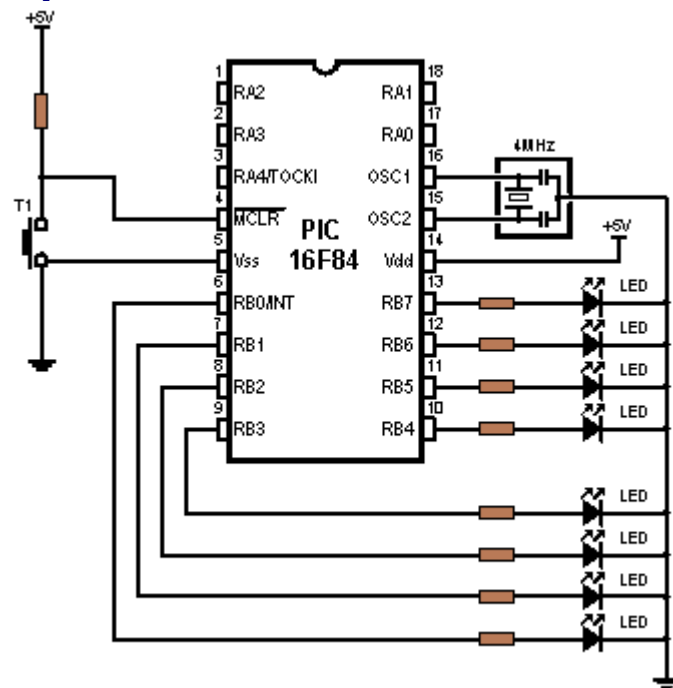
Loop
    goto Loop               ;Main loop

ISR
    bcf INTCON,INTF         ;Clears the flag that indicates RB interrupt
                             ;took place thus enabling detection of
                             ;new interrupts in main program
    btfss PORTB,7           ;Is LED7 on?
    goto Lab1
    bcf PORTB,7             ;If true switch off LED7
    retfie

Lab1
    bsf PORTB,7             ;If false switch on LED7
    retfie
End

```

Interruption sur débordement du Timer TMR0



```

;***** Declaring and configuring a microcontroller *****
        PROCESSOR 16f84
        #include "p16f84.inc"

        __CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Declaring variables *****
        cnt      equ 0x0c

;***** Structure of program memory *****

        ORG      0x00          ;Reset vector
        goto     Main

        ORG      0x04          ;Interrupt vector
        goto     ISR

Main
[
        bsf 3,5
        clrf   TRISB           ;Port B is output
        movlw  .255
        movwf  TRISA           ;Port A is input
        movlw  B'10000100'     ;Set prescaler to TMRO
        movwf  OPTION_REG     ;ps = 32=> TMRO is incremented every 32us
        bcf 3,5
        clrf   PORTB           ;All the diodes are off by default
        bsf   INTCON,TOIE      ;Enable TMRO interrupt
        movlw  .96             ;Initialize TMRO
                                ;Overflow occurs every (255-96)*32us=5.088ms

        movwf  TMRO            ;Start the counter

        bsf   INTCON,GIE       ;Interrupts are globally enabled
        clrf  cnt

loop
        goto  loop            ;Remain at this line

ISR
        movlw  .96             ;Initialize TMRO to ensure next interrupt
                                ;in 5ms

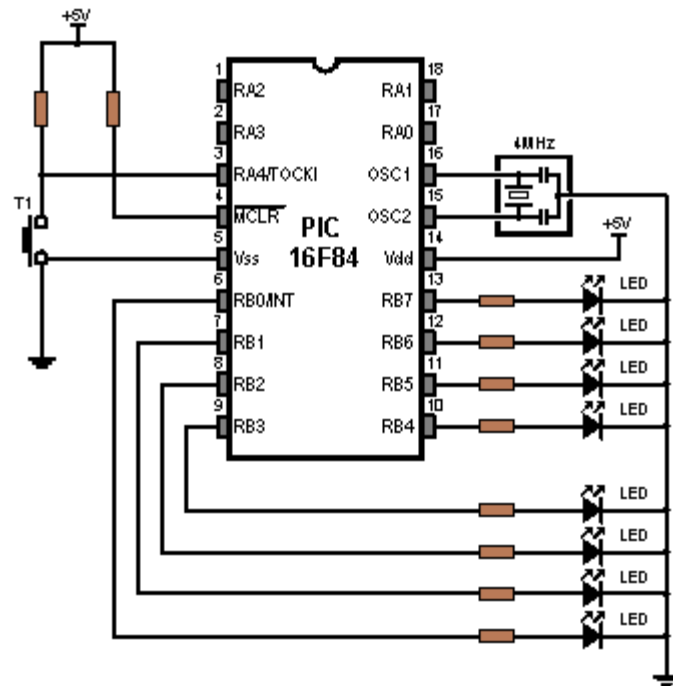
        movwf  TMRO
        bcf   INTCON,TOIF      ;clear int. flag

        incf  cnt,F
        movlw .196             ;Has one second elapsed?(1s~196*5.088 ms)
        subwf cnt,W
        btfss STATUS,Z
        retfie
        comf  PORTB,f          ;If true, complement the values of port B
        clrf  cnt              ;and set the initial value of variable cnt
        retfie                  ;If false, exit the interrupt routine

        End                    ;End of program

```

Interruption sur débordement du TMRO connecté à une entrée externe (TOCKI)



```

;***** Declaring and configuring a microcontroller *****
        PROCESSOR 16f84
        #include "pl6f84.inc"

        __CONFIG _CP_OFF & _WDT_OFF & _PWRTE_ON & _XT_OSC

;***** Declaring constants *****
        num_rev equ .156;

;***** Structure of program memory *****

        ORG      0x00                ; Reset vector
        goto     Main

        ORG      0x04                ; Interrupt vector
        goto     ISR

Main
        bsf 3,5
        clrf    TRISB                ; Port B is input
        movlw   B'11111'
        movwf   TRISA                ; Port A is output
        movlw   B'10100001'
        movwf   OPTION_REG           ; External impulses on T0CKI increment TMRO
        bcf 3,5                       ; ps = 4 TMRO increments every 4 impulses
        clrf    PORTB                ; i.e. 1 revolution = 4 impulses
        bsf     INTCON,T0IE           ; All diodes are off by default
        movlw   .256                  ; Enable TMRO interrupt
        sublw   num_rev               ; Initialize TMRO so that overflow
        movwf   TMRO                  ; occurs every 100 revolutions,
        bsf     INTCON,GIE            ; i.e. TMRO is set to 256-156=100

        movwf   TMRO                  ; Start the counter
        bsf     INTCON,GIE            ; Interrupts are globally enabled

```

```

loop
                                ; Display number of remaining revolutions
                                ; on port B
    movf TMR0,W
    sublw .256                  ; number of remaining revolutions=256-TMR0
    movwf PORTB
    goto loop                   ; Remain at this line

ISR
    movlw .256                  ; Initialize TMR0 so it can count next
                                ; 100 revolutions
    sublw broj_obrtaja
    movwf TMR0

    bcf INTCON,TOIF ; clear int. fleg
    retfie              ; return to main program

End                        ; End of program

```